

PLPE

The cost effective planetary gearbox with the best torque-low heat performance

Our **PLPE** unites the best properties of the Economy Line with a performance advantage. It is cost effective, yet powerful, and generates minimal heat. The optimized output bearing has been designed for high radial and axial forces.

1 High axial and radial forces

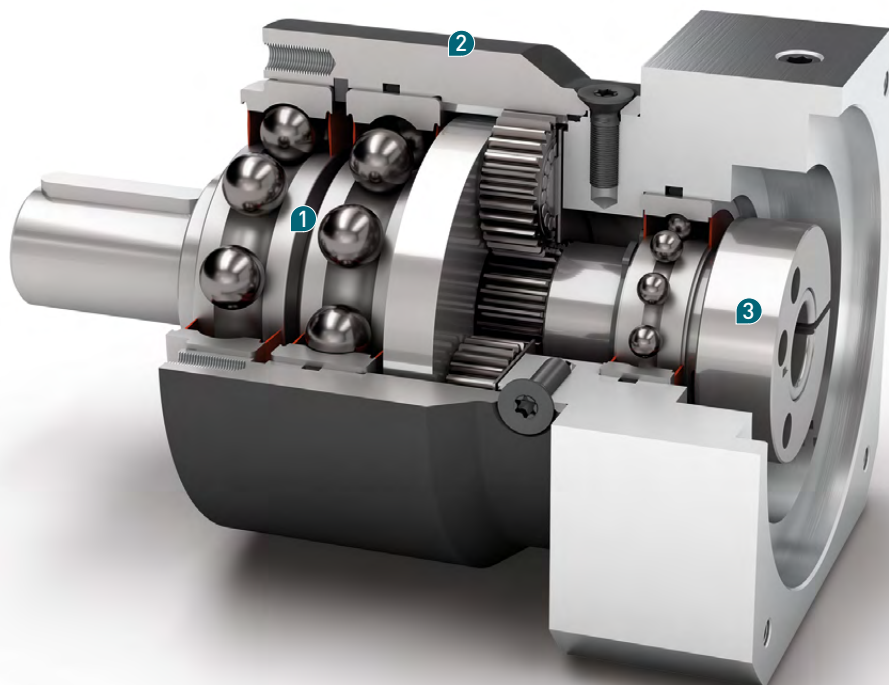
The large tapered roller bearings in the **PLPE** can absorb large radial and axial forces. Your drive elements can therefore be installed directly on the output shaft without the need for additional bearing components. This makes it easy to use and flexible.

2 Best price

The **PLPE** is one of the pillars of our Economy Line. You are given a powerful planetary gearbox with very high energy efficiency – and that at a particularly fair price.

3 Low heat generation at the highest speeds

Its low-friction bearing design and optimized lubrication make the **PLPE** extremely resistant. And thanks to its low heat generation, it also passes the most demanding tests.



- + For any mounting position
- + Individual adaptation of the input flange to the motor
- + Lifetime lubrication for maintenance-free operation
- + Equidirectional rotation
- + Wide range of output shaft designs
- + Clamping systems with optimized mass moment of inertia
- + Precise gearing

Code	Gearbox characteristics			PLPE050	PLPE070	PLPE090	PLPE120	PLPE155	z ⁽¹⁾
	Service life	t _L	h	30000					
	Efficiency at full load ⁽²⁾	η	%	98					1
				97					2
	Min. operating temperature	T _{min}	°C	-25 (-13)					
	Max. operating temperature	T _{max}	(°F)	90 (194)					
	Protection class			IP 54					
S	Standard lubrication			Grease					
F	Food grade lubrication			Grease					
L	Low temperature lubrication ⁽³⁾			Grease					
	Installation position			Any					
S	Standard backlash	j _t	arcmin	< 15	< 10	< 7	< 7	< 8	1
				< 19	< 12	< 9	< 9	< 10	2
	Torsional stiffness ⁽²⁾	c _g	Nm/arcmin (lb _r .in/ arcmin)	0.8 - 1.1 (7 - 10)	2.6 - 3.5 (23 - 31)	7.3 - 9.8 (65 - 87)	20.0 - 27.0 (177 - 239)	38.5 - 52.0 (341 - 460)	1
				0.8 - 1.1 (7 - 10)	2.7 - 3.5 (24 - 31)	7.4 - 9.8 (65 - 87)	20.5 - 27.0 (181 - 239)	39.5 - 52.0 (350 - 460)	2
	Gearbox weight	m _G	kg (lb _m)	0.7 (1.5)	1.5 (3.3)	3 (6.6)	7.5 (16.5)	16.5 (36.4)	1
				0.9 (2.0)	1.8 (4.0)	3.7 (8.2)	9.7 (21.4)	20.5 (45.2)	2
S	Standard surface			Housing: Steel – nitrocarburized and post-oxidized (black)					
	Running noise ⁽⁴⁾	Q _g	dB(A)	58	58	60	65	70	
	Max. bending moment based on the gearbox input flange ⁽⁵⁾	M _b	Nm (lb _r .in)	3 (27)	8 (71)	16 (142)	40 (354)	180 (1593)	
	Motor flange precision			DIN 42955-N					

Output shaft loads			PLPE050	PLPE070	PLPE090	PLPE120	PLPE155	z ⁽¹⁾
Radial force for 20,000 h ⁽⁶⁾⁽⁷⁾	F _{r 20.000 h}	N (lb _f)	800 (180)	1050 (236)	1900 (428)	2500 (563)	5200 (1170)	
Axial force for 20,000 h ⁽⁶⁾⁽⁷⁾	F _{a 20.000 h}		1000 (225)	1350 (304)	2000 (450)	4000 (900)	7000 (1575)	
Radial force for 30,000 h ⁽⁶⁾⁽⁷⁾	F _{r 30.000 h}		700 (158)	900 (203)	1700 (383)	2150 (484)	4600 (1035)	
Axial force for 30,000 h ⁽⁶⁾⁽⁷⁾	F _{a 30.000 h}		800 (180)	1000 (225)	1500 (338)	3000 (675)	6000 (1350)	
Static radial force ⁽⁷⁾⁽⁸⁾	F _{r Stat}		1300 (293)	1650 (371)	3100 (698)	4000 (900)	8400 (1890)	
Static axial force ⁽⁷⁾⁽⁸⁾	F _{a Stat}		1000 (225)	2100 (473)	3800 (855)	5900 (1328)	11000 (2475)	
Tilting moment for 20,000 h ⁽⁶⁾⁽⁸⁾	M _{K 20.000 h}	Nm (lb _r .in)	26 (230)	42 (372)	99 (876)	168 (1487)	497 (4398)	
Tilting moment for 30,000 h ⁽⁶⁾⁽⁸⁾	M _{K 30.000 h}		22 (195)	36 (319)	89 (788)	144 (1274)	440 (3894)	

Moment of inertia			PLPE050	PLPE070	PLPE090	PLPE120	PLPE155	z ⁽¹⁾
Mass moment of inertia ⁽²⁾	J	kgcm ² (lb _r .in.s ² 10 ⁻⁴)	0.015 - 0.030 (0.133 - 0.266)	0.069 - 0.174 (0.611 - 1.540)	0.374 - 0.789 (3.310 - 6.983)	1.419 - 2.764 (12.558 - 24.461)	4.932 - 7.611 (43.648 - 67.357)	1
			0.014 - 0.026 (0.124 - 0.230)	0.064 - 0.126 (0.566 - 1.115)	0.356 - 0.625 (3.151 - 5.531)	1.376 - 2.334 (12.178 - 20.656)	4.759 - 7.108 (42.117 - 62.906)	2

(1) Number of stages
(2) The ratio-dependent values can be retrieved in Tec Data Finder – www.neugart.com
(3) T_{min} = -40°C (-40°F). Optimal operating temperature max. 50°C (122°F)
(4) Sound pressure level from 1 m, measured on input running at n₁=3000 rpm no load; i=5
(5) Max. motor weight* in kg = 0.2 x M_b / motor length in m
* with symmetrically distributed motor weight
* with horizontal and stationary mounting
(6) These values are based on an output shaft speed of n₂=100 rpm
(7) Based on center of output shaft
(8) Other (sometimes higher) values following changes to T_{2n1}, F_r, F_a, cycle, and service life of bearing. Application specific configuration with NCP – www.neugart.com

Output torques			PLPE050	PLPE070	PLPE090	PLPE120	PLPE155	i ⁽¹⁾	z ⁽²⁾
Nominal output torque ⁽³⁾⁽⁴⁾	T _{2N}	Nm (lb.in)	11 (97)	28 (248)	85 (752)	115 (1018)	-	3	1
			15 (133)	33 (292)	90 (797)	155 (1372)	460 (4071)	4	
			13 (115)	30 (266)	82 (726)	172 (1522)	445 (3938)	5	
			8.5 (75)	25 (221)	65 (575)	135 (1195)	-	7	
			6 (53)	18 (159)	50 (443)	120 (1062)	-	8	
			5 (44)	15 (133)	38 (336)	95 (841)	210 (1859)	10	
			12 (106)	33 (292)	97 (858)	157 (1389)	-	9	2
			15 (133)	33 (292)	90 (797)	195 (1726)	-	12	
			13 (115)	33 (292)	82 (726)	172 (1522)	-	15	
			15 (133)	33 (292)	90 (797)	195 (1726)	460 (4071)	16	
			15 (133)	33 (292)	90 (797)	195 (1726)	460 (4071)	20	
			13 (115)	30 (266)	82 (726)	172 (1522)	445 (3938)	25	
			15 (133)	33 (292)	90 (797)	195 (1726)	-	32	
			13 (115)	30 (266)	82 (726)	172 (1522)	460 (4071)	40	
			-	-	-	-	445 (3938)	50	
			7.5 (66)	18 (159)	50 (443)	120 (1062)	-	64	
			5 (44)	15 (133)	38 (336)	95 (841)	210 (1859)	100	
			Max. output torque ⁽⁴⁾⁽⁵⁾	T _{2max}	Nm (lb.in)	17.5 (155)	45 (398)	136 (1204)	
24 (212)	53 (469)	144 (1274)				248 (2195)	736 (6514)	4	
21 (186)	48 (425)	131 (1159)				275 (2434)	712 (6301)	5	
13.5 (119)	40 (354)	104 (920)				216 (1912)	-	7	
9.5 (84)	29 (257)	80 (708)				192 (1699)	-	8	
8 (71)	24 (212)	61 (540)				152 (1345)	336 (2974)	10	
19 (168)	53 (469)	155 (1372)				251 (2221)	-	9	2
24 (212)	53 (469)	144 (1274)				312 (2761)	-	12	
21 (186)	53 (469)	131 (1159)				275 (2434)	-	15	
24 (212)	53 (469)	144 (1274)				312 (2761)	736 (6514)	16	
24 (212)	53 (469)	144 (1274)				312 (2761)	736 (6514)	20	
21 (186)	48 (425)	131 (1159)				275 (2434)	712 (6301)	25	
24 (212)	53 (469)	144 (1274)				312 (2761)	-	32	
21 (186)	48 (425)	131 (1159)				275 (2434)	736 (6514)	40	
-	-	-				-	712 (6301)	50	
12 (106)	29 (257)	80 (708)				192 (1699)	-	64	
8 (71)	24 (212)	61 (540)				152 (1345)	336 (2974)	100	

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(1) Ratios (i=n₁/n₂)
 (2) Number of stages
 (3) Application specific configuration with NCP – www.neugart.com
 (4) Values for feather key (code "A"): for repeated load
 (5) 30,000 rotations of the output shaft permitted; see page 128

Output torques			PLPE050	PLPE070	PLPE090	PLPE120	PLPE155	i ⁽¹⁾	z ⁽²⁾
Emergency stop torque ⁽³⁾	T _{2Stop}	Nm (lb _f .in)	22,5 (199)	66 (584)	180 (1593)	390 (3452)	-	3	1
			30 (266)	88 (779)	240 (2124)	520 (4602)	920 (8142)	4	
			36 (319)	80 (708)	220 (1947)	500 (4425)	890 (7877)	5	
			26 (230)	80 (708)	178 (1575)	340 (3009)	-	7	
			27 (239)	80 (708)	190 (1682)	380 (3363)	-	8	
			27 (239)	80 (708)	200 (1770)	480 (4248)	420 (3717)	10	
		33 (292)	88 (779)	260 (2301)	500 (4425)	-	9	2	
		40 (354)	88 (779)	240 (2124)	520 (4602)	-	12		
		36 (319)	88 (779)	220 (1947)	500 (4425)	-	15		
		40 (354)	88 (779)	240 (2124)	520 (4602)	920 (8142)	16		
		40 (354)	88 (779)	240 (2124)	520 (4602)	920 (8142)	20		
		36 (319)	80 (708)	220 (1947)	500 (4425)	890 (7877)	25		
		40 (354)	88 (779)	240 (2124)	520 (4602)	-	32		
		36 (319)	80 (708)	220 (1947)	500 (4425)	920 (8142)	40		
		-	-	-	-	890 (7877)	50		
		27 (239)	80 (708)	190 (1682)	380 (3363)	-	64		
		27 (239)	80 (708)	200 (1770)	480 (4248)	420 (3717)	100		

Input speeds			PLPE050	PLPE070	PLPE090	PLPE120	PLPE155	i ⁽¹⁾	z ⁽²⁾
Average thermal input speed at T _{2N} and S1 ⁽⁴⁾⁽⁵⁾	n _{1N}	rpm	5000	4500 ⁽⁶⁾	3250 ⁽⁶⁾	2650 ⁽⁶⁾	-	3	1
			5000	4500 ⁽⁶⁾	3750 ⁽⁶⁾	2800 ⁽⁶⁾	1800 ⁽⁶⁾	4	
			5000	4500	4000 ⁽⁶⁾	3100 ⁽⁶⁾	2150 ⁽⁶⁾	5	
			5000	4500	4000	3500 ⁽⁶⁾	-	7	
			5000	4500	4000	3500	-	8	
			5000	4500	4000	3500	3000	10	
			5000	4500	4000 ⁽⁶⁾	3500 ⁽⁶⁾	-	9	2
			5000	4500	4000	3500 ⁽⁶⁾	-	12	
			5000	4500	4000	3500 ⁽⁶⁾	-	15	
			5000	4500	4000	3500 ⁽⁶⁾	2900 ⁽⁶⁾	16	
			5000	4500	4000	3500	3000 ⁽⁶⁾	20	
			5000	4500	4000	3500	3000 ⁽⁶⁾	25	
			5000	4500	4000	3500	-	32	
			5000	4500	4000	3500	3000	40	
			-	-	-	-	3000	50	
			5000	4500	4000	3500	-	64	
			5000	4500	4000	3500	3000	100	
			Max. mechanical input speed ⁽⁴⁾	n _{1Limit}		18000	13000	7000	

⁽¹⁾ Ratios (i=n₁/n₂)

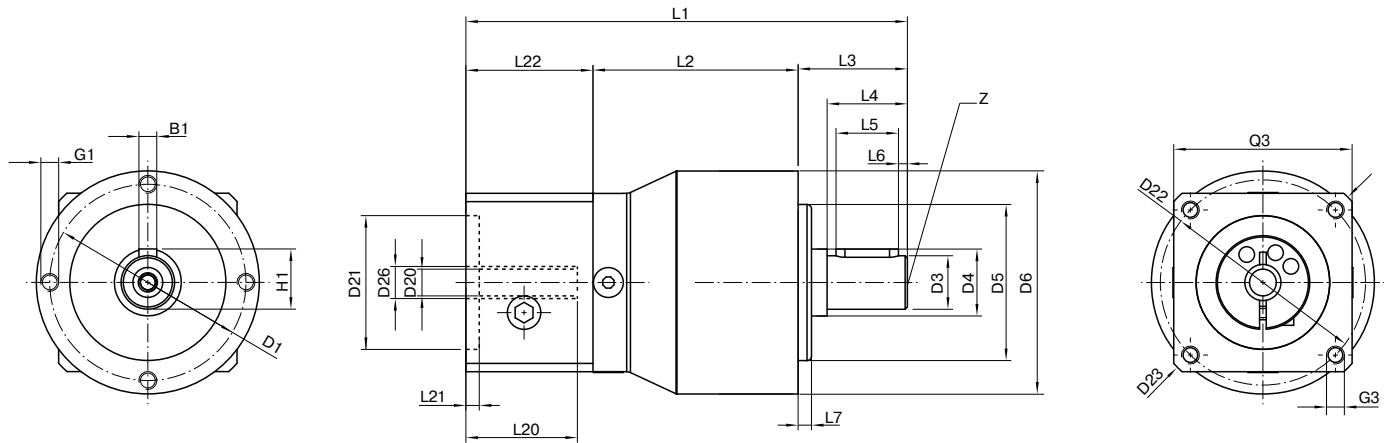
⁽²⁾ Number of stages

⁽³⁾ Permitted 1000 times

⁽⁴⁾ Application-specific speed configurations with NCP – www.neugart.com

⁽⁵⁾ See page 128 for the definition

⁽⁶⁾ Average thermal input speed at 50% T_{2N} and S1



Drawing corresponds to a PLPE050 / 1-stage / output shaft with feather key / 8 mm clamping system / motor adaptation – one part / B5 flange type motor
 All other variants can be retrieved in the Tec Data Finder at www.neugart.com

Geometry ⁽¹⁾			PLPE050	PLPE070	PLPE090	PLPE120	PLPE155	z ⁽²⁾	Code					
Pitch circle diameter output	D1		44 (1.732)	62 (2.441)	80 (3.150)	108 (4.252)	140 (5.512)							
Shaft diameter output	D3	k7	12 (0.472)	16 (0.630)	22 (0.866)	32 (1.260)	40 (1.575)							
Shaft collar output	D4		15 (0.591)	30 (1.181)	35 (1.378)	50 (1.969)	55 (2.165)							
Centering diameter output	D5	h7	35 (1.378)	52 (2.047)	68 (2.677)	90 (3.543)	120 (4.724)							
Housing diameter	D6		50 (1.969)	70 (2.756)	90 (3.543)	120 (4.724)	155 (6.102)							
Mounting thread x depth	G1	4x	M4x8	M5x8	M6x9	M8x20	M10x20							
Min. total length	L1		94 (3.701)	111 (4.370)	147 (5.787)	192 (7.559)	275.5 (10.846)	1						
			106.5 (4.193)	124 (4.882)	165 (6.496)	219.5 (8.642)	320 (12.598)	2						
Housing length	L2		46 (1.811)	51 (2.008)	67.5 (2.657)	76.5 (3.012)	100 (3.937)	1						
			58.5 (2.303)	64 (2.520)	85.5 (3.366)	104 (4.094)	144.5 (5.689)	2						
Shaft length output	L3		24.5 (0.965)	36 (1.417)	46 (1.811)	68 (2.677)	97 (3.819)							
Centering depth output	L7		3 (0.118)	3 (0.118)	4 (0.157)	5 (0.197)	8 (0.315)							
Clamping system diameter input	D26		More information on page 117											
Motor shaft diameter j6/k6	D20		The dimensions vary with the motor/gearbox flange. The input flange geometries can be retrieved for each specific motor in Tec Data Finder at www.neugart.com											
Max. permis. motor shaft length	L20													
Min. permis. motor shaft length														
Centering diameter input	D21													
Centering depth input	L21													
Pitch circle diameter input	D22													
Motor flange length	L22													
Diagonal dimension input	D23													
Mounting thread x depth	G3	4x												
Flange cross section input	Q3	■												
Output shaft with feather key (DIN 6885-1)								A 4x4x14	A 5x5x25	A 6x6x32	A 10x8x50	A 12x8x70		A
Feather key width (DIN 6885-1)	B1							4 (0.157)	5 (0.197)	6 (0.236)	10 (0.394)	12 (0.472)		
Shaft height including feather key (DIN 6885-1)	H1		13.5 (0.531)	18 (0.709)	24.5 (0.965)	35 (1.378)	43 (1.693)							
Shaft length from shoulder	L4		18 (0.709)	28 (1.102)	36 (1.417)	58 (2.283)	82 (3.228)							
Feather key length	L5		14 (0.551)	25 (0.984)	32 (1.260)	50 (1.969)	70 (2.756)							
Distance from shaft end	L6		2 (0.079)	2 (0.079)	2 (0.079)	4 (0.157)	6 (0.236)							
Center hole (DIN 332, type DR)	Z		M4x10	M5x12.5	M8x19	M12x28	M16x36							
Smooth output shaft									B					
Shaft length from shoulder	L4		18 (0.709)	28 (1.102)	36 (1.417)	58 (2.283)	82 (3.228)							

⁽¹⁾ Dimensions in mm (in)

⁽²⁾ Number of stages